# The generation of internal waves by vibrating elliptic cylinders. Part 2. Approximate viscous solution 

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An approximate theory is given for the generation of internal gravity waves in a viscous Boussinesq fluid by the rectilinear vibrations of an elliptic cylinder. A parameter $\lambda$ which is proportional to the square of the ratio of the thickness of the oscillatory boundary layer that surrounds the cylinder to a typical dimension of its cross-section is introduced. When $\lambda \ll 1$ (or equivalently when the Reynolds number $R \gg 1$ ), the viscous boundary condition at the surface of the cylinder may to first order in $\lambda$ be replaced by the inviscid one. A viscous solution is proposed for the case $\lambda \ll 1$ in which the Fourier representation of the stream function found in Part 1 (Hurley 1997) is modified by including in the integrands a factor to account for viscous dissipation. In the limit $\lambda \rightarrow 0$ the proposed solution becomes the inviscid one at each point in the flow field.

For ease of presentation the case of a circular cylinder of radius $a$ is considered first and we take $a$ to be the typical dimension of its cross-section in the definition of $\lambda$ above. The accuracy of the proposed approximate solution is investigated both analytically and numerically and it is concluded that it is accurate throughout the flow field if $\lambda$ is sufficiently small, except in a small region near where the characteristics touch the cylinder where viscous effects dominate.

Computations indicate that the velocity on the centreline on a typical beam of waves, at a distance $s$ along the beam from the centre of the cylinder, agrees, within about $1 \%$, with the (constant) inviscid values provided $\lambda s / a$ is less than about $10^{-3}$. This result is interpreted as indicating that those viscous effects which originate from the characteristics that touch the cylinder (places where the inviscid velocity is singular) reach the centreline of the beam when $\lambda s / a$ is about $10^{-3}$. For larger values of $s$, viscous effects are significant throughout the beam and the velocity profile of the beam changes until it attains, within about $1 \%$ when $\lambda s / a$ is about 2 , the value given by the similarity solution obtained by Thomas \& Stevenson (1972). For larger values of $\lambda s / a$, their similarity solution applies.
In an important paper Makarov et al. (1990) give an approximate solution for the circular cylinder that is very similar to ours. However, it does not reduce to the inviscid one when the viscosity is taken to be zero.
Finally it is shown that our results for a circular cylinder apply, after small modifications, to all elliptical cylinders.

## 1. Introduction

The inviscid theory described in Part 1, Hurley (1997), has two features that limit its applicability to a real fluid of small viscosity. First, the fluid velocities have inverse
square-root singularities at all points of the characteristics that touch the vibrating cylinder, so that the kinetic energy of the fluid per unit length of characteristic is infinite. Also, the fluid velocities do not decay with increasing distance from the cylinder.

In the present paper we investigate how these two defects are alleviated if the fluid is assumed to be viscous while remaining with a linearized treatment. The basic equations are given in $\S 2$. In $\S 3$ we propose an approximate solution to the viscous flow, for the case when the Reynolds number $R$, defined in §2.1, is large. Specifically, the Fourier decompositions of the stream function of the inviscid solution, obtained in Part 1, are modified by including in the integrands factors to account for viscous dissipation. The proposed approximate solution applies to all elliptic cylinders but for ease of presentation it is described in $\S 3$ for the case of a circular cylinder. Section 4 gives extensive numerical results and in $\S 5$ our results are compared with both theoretical and experimental ones obtained by other investigations. Finally in $\S 6$ it is pointed out that the main properties of the flow for a circular cylinder also hold for all elliptic cylinders.

## 2. Basic equations

The problem is the same as that considered in Part 1, except that the stratified fluid of constant Brunt-Väisälä frequency $N$ surrounding the elliptical cylinder is now supposed to be viscous of kinematic viscosity $\nu$. As in Part 1, the ellipse has semi-axes $a$ and $b$, the former being inclined at an angle $\theta$ to the horizontal. We introduce Cartesian axes, the $x$-axis being horizontal and the $y$-axis vertically up, and the origin of the coordinate system is at the centre of the cylinder. We suppose that the velocity of each point of the surface of the cylinder is $(U, V) \exp (-\mathrm{i} \omega t)$ where $t$ is the time, and $\omega$ the angular frequency. The fluid motions may be described in terms of a stream function $\psi(x, y) \exp (-\mathrm{i} \omega t)$ such that the velocity $(u, v)$ is

$$
\begin{equation*}
u=-\frac{\partial \psi}{\partial y} \mathrm{e}^{-\mathrm{i} \omega t}, \quad v=\frac{\partial \psi}{\partial x} \mathrm{e}^{-\mathrm{i} \omega t}, \tag{2.1}
\end{equation*}
$$

and $\psi$ satisfies

$$
\begin{equation*}
\eta^{2} \frac{\partial^{2} \psi}{\partial x^{2}}-\frac{\partial^{2} \psi}{\partial y^{2}}+\frac{\mathrm{i} \nu}{\omega} \nabla^{4} \psi=0 \tag{2.2}
\end{equation*}
$$

where

$$
\begin{equation*}
\eta^{2}=N^{2} / \omega^{2}-1 . \tag{2.3}
\end{equation*}
$$

In addition, the velocities must vanish as $(x, y)$ tends to infinity. The boundary condition on the cylinder is discussed in $\S 2.1$ below.

We introduce the coordinates

$$
\begin{equation*}
\sigma_{+}=x \sin (\mu)-y \cos (\mu), \quad s_{+}=x \cos (\mu)+y \sin (\mu), \tag{2.4}
\end{equation*}
$$

where $0<\mu<\pi / 2$ and

$$
\begin{equation*}
0<\eta=\cot (\mu) . \tag{2.5}
\end{equation*}
$$

In terms of them, (2.2) is

$$
\begin{equation*}
\frac{\partial^{2} \psi}{\partial \sigma_{+} \partial s_{+}}+\cot (2 \mu) \frac{\partial^{2} \psi}{\partial s_{+}^{2}}+\frac{\mathrm{i} v}{2 \omega \eta}\left(\frac{\partial^{2} \psi}{\partial \sigma_{+}^{4}}+2 \frac{\partial^{4} \psi}{\partial \sigma_{+}^{2} \partial s_{+}^{2}}+\frac{\partial^{4} \psi}{\partial s_{+}^{4}}\right)=0 . \tag{2.6}
\end{equation*}
$$

We also introduce the coordinates

$$
\begin{equation*}
\sigma_{-}=x \sin (\mu)+y \cos (\mu), \quad s_{-}=-x \cos (\mu)+y \sin (\mu) . \tag{2.7}
\end{equation*}
$$



Figure 1. Notation. (a) $O \sigma_{+} s_{+}$axes, (b) $O \sigma_{-} s_{-}$axes.

In terms of these, (2.2) is

$$
\begin{equation*}
\frac{\partial^{2} \psi}{\partial \sigma_{-} \partial s_{-}}-\cot (2 \mu) \frac{\partial^{2} \psi}{\partial s_{-}^{2}}-\frac{\mathrm{i} v}{2 \omega \eta}\left(\frac{\partial^{4} \psi}{\partial \sigma_{-}^{4}}+2 \frac{\partial^{4} \psi}{\partial \sigma_{-}^{2} \partial s_{-}^{2}}+\frac{\partial^{4} \psi}{\partial s_{-}^{4}}\right)=0 \tag{2.8}
\end{equation*}
$$

Figure 1 gives the directions of the $O \sigma_{+} s_{+}$and the $O \sigma_{-} s_{-}$axes.
We now follow Thomas \& Stevenson (1972) in introducing their 'boundary-layer approximation' by assuming that, in (2.6), derivatives with respect to $\sigma_{+}$are much larger than those with respect to $s_{+}$. With this assumption, the equation is approximated by

$$
\begin{equation*}
\frac{\partial^{2} \psi}{\partial \sigma_{+} \partial s_{+}}+\frac{\mathrm{i} v}{2 \omega \eta}\left(\frac{\partial^{4} \psi}{\partial \sigma_{+}^{4}}\right)=0 \tag{2.9}
\end{equation*}
$$

Similarly, (2.8) is approximated by

$$
\begin{equation*}
\frac{\partial^{2} \psi}{\partial \sigma_{-} \partial s_{-}}-\frac{\mathrm{i} v}{2 \omega \eta}\left(\frac{\partial^{4} \psi}{\partial \sigma_{-}^{4}}\right)=0 \tag{2.10}
\end{equation*}
$$

### 2.1. The boundary condition on the cylinder

The vibrating cylinder will be surrounded by an oscillatory boundary layer whose thickness is order $\delta$, where

$$
\begin{equation*}
\delta=(\nu / \omega)^{1 / 2} \tag{2.11}
\end{equation*}
$$

see Rosenhead (1963, p. 383) and Batchelor (1967, §5.13, p. 354).
We define

$$
\begin{align*}
\lambda & =\nu /\left(2 c^{2} \omega \eta\right)  \tag{2.12}\\
& =1 /(2 \eta R), \tag{2.13}
\end{align*}
$$

where $c$ is a typical dimension of the ellipse and

$$
\begin{equation*}
R=c^{2} \omega / v \tag{2.14}
\end{equation*}
$$

is the Reynolds number.
Equations (2.11) and (2.12) show that an alternative expression for $\lambda$ is

$$
\begin{equation*}
\lambda=\frac{1}{2 \eta}\left(\frac{\delta}{c}\right)^{2} \tag{2.15}
\end{equation*}
$$

We suppose that $\lambda \ll 1$ or equivalently by (2.13) that $R \gg 1$. Then to first order in $\lambda$
(Rosenhead 1963) the viscous no-slip boundary condition at the surface of the ellipse may be replaced by the inviscid one which is

$$
\begin{equation*}
\psi=V x-U y \tag{2.16}
\end{equation*}
$$

We also suppose that

$$
\begin{equation*}
U /(\omega c) \ll 1 \quad \text { and } \quad V /(\omega c) \ll 1 \tag{2.17}
\end{equation*}
$$

because these must be satisfied for the present analysis, which is based on the 'acoustic limit', to be valid (Bell 1975).

## 3. Approximate viscous solution

It is convenient to consider the case of the circular cylinder first. We take its radius $a$ as its typical dimension so that the parameter $\lambda$ introduced in $\S 2.1$ above becomes

$$
\begin{equation*}
\lambda=\nu /\left(2 a^{2} \omega \eta\right) \tag{3.1}
\end{equation*}
$$

The proposed solution is

$$
\begin{equation*}
\psi=\psi_{+}\left(\sigma_{+}, s_{+}\right)+\psi \psi_{-}\left(\sigma_{-}, s_{-}\right) \tag{3.2}
\end{equation*}
$$

where

$$
\begin{array}{ll}
\psi_{+}=\mp \mathrm{i} \alpha_{+} a \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\mp K^{3} \lambda \frac{s_{+}}{a} \pm \mathrm{i} K \frac{\sigma_{+}}{a}\right) \mathrm{d} K, & \pm s_{+}>0, \\
\psi_{-}= \pm \mathrm{i} \alpha_{-} a \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\mp K^{3} \lambda \frac{s_{-}}{a} \mp \mathrm{i} K \frac{\sigma_{-}}{a}\right) \mathrm{d} K, & \pm s_{-}>0 \tag{3.4}
\end{array}
$$

and $\alpha_{+}$and $\alpha_{-}$take the values given by (3.26) and (3.27) of Part 1: namely

$$
\begin{align*}
& \alpha_{+}=\frac{1}{2}(V \sin (\mu)+U \cos (\mu)+\mathrm{i}[V \cos (\mu)-U \sin (\mu)])  \tag{3.5}\\
& \alpha_{-}=\frac{1}{2}(V \sin (\mu)-U \cos (\mu)+\mathrm{i}[V \cos (\mu)+U \sin (\mu)]) \tag{3.6}
\end{align*}
$$

We focus attention on the beam of waves in the first quadrant for which

$$
\begin{equation*}
\psi_{+}=-\mathrm{i} \alpha_{+} a \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(-K^{3} \lambda \frac{s_{+}}{a}+\mathrm{i} K \frac{\sigma_{+}}{a}\right) \mathrm{d} K, \quad s_{+}>0 \tag{3.7}
\end{equation*}
$$

We note that at any point $\left(\sigma_{+}, s_{+}\right)$the limit as $\nu \rightarrow 0$ of $\psi_{+}$given by (3.7) is that given by (3.31) of Part 1, the inviscid solution. The decay factor $\exp \left(-K^{3} \lambda s_{+} / a\right)$ in the integrand of (3.7) is the same as that used in Townsend (1966), Lighthill (1978) and Makarov, Neklyudov \& Chasheckin (1990).

We also note that $\psi_{+}$and $\psi_{-}$given by (3.3) and (3.4) satisfy (2.9) and (2.10) respectively which were obtained from the exact equations (2.6) and (2.8) by applying the boundary-layer approximation. In Appendices A and B we give derivations of (3.3) and (3.4) from the exact equations and conclude that if $\lambda \ll 1$ they provide a good approximation almost everywhere throughout the flow field. Their accuracy is also investigated numerically in $\S 4.4$ below.

### 3.1. The smoothness of our solution

It is important to investigate the smoothness of the solution given by (3.3) on the two rays $s_{+}=0,\left|\sigma_{+}\right|>a$, for if it were not smooth on them there would be singularities in its flow field.

As $s_{+}$tends to $\pm 0, \psi_{+}$given by (3.3) attains the limiting values given by (3.35)-(3.37) of Part 1. Hence $\psi_{+}$is continuous on $s_{+}=0,\left|\sigma_{+}\right|>a$ and so too will be all its derivatives with respect to $\sigma_{+}$. (We remark though that formal differentiation of the integral representations of $\psi_{+}$with respect to $\sigma_{+}$, and then setting $s_{+}=0$ leads to
divergent integrals). Also $\psi_{+}$given by (3.3) satisfies (2.9) which may be integrated once to give (noting that the various derivatives of $\psi_{+}$tend to zero as $\sigma_{+}$tends to plus or minus infinity)

$$
\begin{equation*}
\frac{\partial \psi_{+}}{\partial s_{+}}+\mathrm{i} \lambda a^{2} \frac{\partial^{3} \psi_{+}}{\partial \sigma_{+}^{3}}=0 \tag{3.8}
\end{equation*}
$$

which shows that the first derivative of $\psi_{+}$with respect to $s_{+}$is continuous across $s_{+}=0,\left|\sigma_{+}\right|>a$. Higher derivatives with respect to $s_{+}$, and cross-derivatives are then handled similarly.

We conclude that $\psi_{+}$given by (3.3) is infinitely differentiable with respect to both variables everywhere in the plane except on the line segment $s_{+}=0$ within the circle. A similar result holds for $\psi_{-}$.

### 3.2. Further consideration of the boundary condition on the cylinder

We note that in the inviscid solution given by (3.42) of Part $1, \psi_{+}$is independent of $s_{+}$. We denote this value by $\psi_{+}^{i}$. Now in our proposed solution given by (3.7), $\psi_{+}$is a continuous function of $\lambda s_{+} / a$ up to the line $s_{+}=0$ on which it equals $\psi_{+}^{i}$. Hence $\left|\psi_{+}-\psi_{+}^{i}\right|$ can be made arbitrarily small provided $\lambda s_{+} / a<\delta$ for some $\delta$. Now the equation of the cylinder in the first quadrant is $s_{+} / a=\left(1-\sigma_{+}^{2} / a^{2}\right)^{1 / 2}$. Hence, since $\left(1-\sigma_{+}^{2} / a^{2}\right)^{1 / 2}$ is bounded, the inequality $\lambda s_{+} / a<\delta$ can be satisfied if $\lambda$ is sufficiently small. We therefore conclude that on the surface of the cylinder $\psi_{+}$differs from $\psi_{+}^{i}$ by an amount that tends to zero with $\lambda$. A similar argument applies to $\psi_{+}$on $s_{+}<0$ and to $\psi_{-}$on $s_{-}<0$ and $s_{-}>0$.

Hence our solution will satisfy the inviscid boundary condition (2.16) and hence, by the remarks in $\S 2.1$, the viscous one to leading order in $\lambda$ with arbitrarily small relative error if $\lambda$ is sufficiently small.

## 4. Numerical results

To save repeated writing of the long expressions in equations like (3.3) and (3.4) and similar formulae for their derivatives, we define functions $I_{e}$ and $I_{o}$ as follows:
where

$$
\begin{align*}
& I_{e}(n ; w, d)=\int_{0}^{\infty} K^{n} J_{1}(K) \exp \left(-d K^{3}\right) \cos (w K) \mathrm{d} K  \tag{4.1}\\
& I_{0}(n ; w, d)=\int_{0}^{\infty} K^{n} J_{1}(K) \exp \left(-d K^{3}\right) \sin (w K) \mathrm{d} K \tag{4.2}
\end{align*}
$$

$$
\begin{equation*}
d=\lambda s_{+} / a \quad \text { and } \quad w=\sigma_{+} / a \tag{4.3}
\end{equation*}
$$

4.1. The velocity profiles in the beams and beam width

Equations (3.7) and (4.1)-(4.3) show that for the beam of waves in the first quadrant

$$
\begin{equation*}
\psi_{+}=-\mathrm{i} \alpha_{+} a\left[I_{e}(-1 ; w, d)+\mathrm{i} I_{o}(-1 ; w, d)\right] \tag{4.4}
\end{equation*}
$$

The velocity components obtained by differentiation of this equation are

$$
\begin{gather*}
\frac{\partial \psi_{+}}{\partial \sigma_{+}}=\alpha_{+}\left[I_{e}(0 ; w, d)+\mathrm{i} I_{o}(0 ; w, d)\right]  \tag{4.5}\\
\frac{\partial \psi_{+}}{\partial s_{+}}=\mathrm{i} \alpha_{+} \lambda\left[I_{e}(2 ; w, d)+\mathrm{i} I_{o}(2 ; w, d)\right] \tag{4.6}
\end{gather*}
$$

The resulting profiles of the waves will be expressed in two ways.
First, we give values of the real and imaginary parts of $\left(1 / \alpha_{+}\right)\left(\partial \psi_{+} / \partial \sigma_{+}\right)$, i.e. values of $I_{e}(0 ; w, d)$ and $I_{o}(0 ; w, d)$ respectively. These are given in figure 2 for various values


Figure 2. The $I_{e}$ and $I_{o}$ functions defining the velocity component $\partial \psi_{+} / \partial \sigma_{+}$in the beams. (a) $I_{e}(0$; $w, d)$ and (b) $I_{o}(0 ; w, d)$, integer $d$ from 1 to 8. (c) $I_{e}(0 ; w, d), d=2^{-j}$ and (d) $I_{o}(0 ; w, d), d=2^{-j} j$ from 0 to 8 .


Figure 3. Wave forms $\left.\operatorname{Re}\left(\partial \psi_{+} / \partial \sigma_{+}\right) \exp (-\mathrm{i} \omega t)\right)$ at successive instants of time for a circular cylinder executing horizontal oscillations. $d=2^{-7}, \omega t=\frac{1}{8} k \pi, k=0,1,2, \ldots, 7$.


Figure 4. The beam width: upper curve for the finite cylinder, lower curve the far-field similarity solution (equation (4.8)).
of $d$, the smallest being $1 / 256$. The values of the inviscid solutions are plotted in Part 1 , figure 4 , and we see that the viscous profiles approach the inviscid ones, albeit rather slowly, as $d$ tends to zero.

In the second method of presentation figure 3 gives, for the case $V=0$, the velocity profiles, $\operatorname{Re}\left(\left(\partial \psi_{+} / \partial \sigma_{+}\right) \exp (-i \omega t)\right)$ at successive instants of time. In particular, the velocity profiles for $d<128$ are bimodal, in that the envelope of the curves has two maxima (Makarov et al. 1990).

Another quantity related to the velocity is the width of the beam. We define the width of the beam to be $2 c_{w}$ where $c_{w}$ satisfies $I_{e}\left(0 ; c_{w} / a, d\right)=0$. Approximate values for the zero $c_{w} / a$ can be read from figure 2 . More accurate values can be obtained by numerically solving for the zero $c_{w} / a$ from (4.1). These values of $c_{w} / a$ are compared in figure 4 with the asymptotics, at large $d$, given by (4.8) below.

For $d$ small, the beam width falls below 1 , its minimum being about 0.9 . Decreasing $d$ further to really tiny values results in the beam width increasing, presumably tending to 1 as $d \rightarrow 0+$.

### 4.2. Solution at large distances from the cylinder

For large values of $d$, the major contribution to the integrals in (3.3) comes from small values of $K$ so that we may replace $J_{1}(K)$ therein by $\frac{1}{2} K$. Thus, for example,

$$
\begin{equation*}
\frac{\partial \psi_{+}}{\partial \sigma_{+}} \sim \frac{\alpha_{+}}{2} \int_{0}^{\infty} K \exp \left(-K^{3} d+\mathrm{i} w K\right) \mathrm{d} K, \quad d \rightarrow \infty, \tag{4.7}
\end{equation*}
$$

where $d$ and $w$ are defined in (4.3). We recognize (4.7) as the solution obtained by Thomas \& Stevenson (1972): see also Lighthill (1978, equation (343)). More generally, we have

$$
\begin{aligned}
& 2 I_{e}(n ; w, d) \sim \int_{0}^{\infty} K^{n+1} \exp \left(-d K^{3}\right) \cos (w K) \mathrm{d} K=d^{-(n+2) / 3} c_{n}\left(w d^{-1 / 3}\right), \\
& 2 I_{o}(n ; w, d) \sim \int_{0}^{\infty} K^{n+1} \exp \left(-d K^{3}\right) \sin (w K) \mathrm{d} K=d^{-(n+2) / 3} s_{n}\left(w d^{-1 / 3}\right) .
\end{aligned}
$$

The notation $c_{n}$ and $s_{n}$ is that used in Thomas \& Stevenson (1972). We remark that functions $c_{n}$ and $s_{n}$ can be written in closed forms, in terms of generalized hypergeometric functions (see Hurley \& Keady 1996). The same functions occur in the singular solution of Makarov et al. (1990).

Profiles given by (4.7) are given in Thomas \& Stevenson (1972), figures 2 and 3. It is clear that the results from our computations using (3.3) at larger $d$, as shown in our figures 2 and 3 herein, are similar. Detailed checks are given in Hurley \& Keady (1996).

It is also possible to derive asymptotics for the beam width $c_{w}$ for large values of $d$. We find

$$
\begin{equation*}
c_{w} / a \sim 2.15323 d^{1 / 3}, \quad d \gg 1 . \tag{4.8}
\end{equation*}
$$

Higher approximations are given in Hurley \& Keady (1996).

### 4.3. The solution on the centreline of the beam

For $w=0, I_{o}(n ; 0, d)=0$ and Mathematica 2.2 is able to evaluate the $I_{e}(n ; 0, d)$ integrals of (4.1) explicitly in terms of generalized hypergeometric functions. Here is its result for the integral - from just one obvious line of Mathematica - associated with the centreline velocity:

$$
\begin{aligned}
I_{e}(0 ; 0, d)= & 1-{ }_{p} F_{q}\left(\left\{\frac{1}{2}\right\},\left\{\frac{1}{3}, \frac{1}{3}, \frac{2}{3}, \frac{2}{3}\right\}, \frac{-1}{11664 d^{2}}\right) \\
& +\frac{\Gamma\left(\frac{2}{3}\right)_{p} F_{q}\left(\left\{\frac{5}{6}\right\},\left\{\frac{2}{3}, \frac{2}{3}, 1, \frac{4}{3}\right\}, \frac{-1}{11664 d^{2}}\right)}{6 d^{2 / 3}}-\frac{\Gamma\left(\frac{4}{3}\right)_{p} F_{q}\left(\left\{\frac{7}{6}\right\},\left\{1, \frac{4}{3}, \frac{4}{3}, \frac{5}{3}\right\}, \frac{-1}{11664 d^{2}}\right)}{48 d^{4 / 3}} .
\end{aligned}
$$

We have checked Mathematica's numerical results against independent numerical evaluations of the integral. The closed form facilitates evaluation of $I_{e}(0 ; 0, d)$ at much smaller values of $d$ than was practical for general values of $w$. As regards asymptotic analyses, Mathematica's representation is still better for the case $d$ large, and, at least at version 2.2, it does not seem straightforward to extract asymptotics for $d$ small. Nevertheless, its numeric capabilities with these special functions is good into values where $d$ is small.
Values of $I_{e}(0 ; 0, d)$, which, by (4.5) is $1 / \alpha_{+}$times the centreline velocity, are compared in figure $5(a)$ with the asymptotic values given by (4.7) which are

$$
\begin{equation*}
I_{e}(0 ; 0, d) \sim \frac{1}{6} \Gamma\left(\frac{2}{3}\right) d^{-2 / 3} \doteq 0.226 d^{-2 / 3}, \quad d \gg 1 . \tag{4.9}
\end{equation*}
$$

The figure shows that the similarity solution is a good approximation for $d>2$.
We now discuss the results for small values of $d$, where we expect the inviscid theory to hold. In this theory, each quantity is independent of $s_{+}$. We therefore expect $\psi_{+}$, $\partial \psi_{+} / \partial \sigma_{+}$and $\partial \psi_{+} / \partial s_{+}$to tend to appropriate values, independent of $d$, for $d$ small.
For $d=0$ and $w=0$, equation (4.4) gives

$$
\psi_{+}=-\mathrm{i} \alpha_{+} a I_{e}(-1 ; 0,0)=-\mathrm{i} \alpha_{+} a,
$$

the latter by consideration of the inviscid $\psi_{+}$. Hence we expect

$$
\begin{equation*}
I_{e}(-1 ; 0, d) \rightarrow 1 \quad \text { as } \quad d \rightarrow 0 \tag{4.10}
\end{equation*}
$$

The other limiting behaviours may similarly be shown to be

$$
\begin{equation*}
I_{e}(0 ; 0, d) \rightarrow 1 \quad \text { as } \quad d \rightarrow 0, \tag{4.11}
\end{equation*}
$$

and

$$
\begin{equation*}
I_{e}(2 ; 0, d) \rightarrow 0 \quad \text { as } \quad d \rightarrow 0 . \tag{4.12}
\end{equation*}
$$



Figure 5. $I_{e}(0 ; 0, d)(a)$ for large $d$ and its asymptotics; $(b)$ for small $d$.

Some indication of the limit (4.11) is evident at the left-hand end of figure $5(a)$. However, the behaviour at small $d$ is rather non-uniform. The overshoot to just beyond 1 , before falling back, is evident in the figure. Figure $5(b)$ plots $I_{e}(0 ; 0, d)$ at small values of $d$. (Computations for other values of $n$, with particular attention to small values of $d$, are reported in detail in Hurley \& Keady 1996.) The computations accord with the limits above and show that (4.10) and (4.11) are within $1 \%$ of being attained if $d<10^{-3}$.

The results discussed earlier in this section suggest that it is convenient to split the range $0<d<\infty$ into three sub-ranges as follows.

Region I is the range $0<d<10^{-3}$. At $d=0$ the profile is the inviscid one and, as $d$ is increased, viscous effects extend inwards from $w= \pm 1$ and reach the centreline after about $d=10^{-3}$. The velocity profile across the beam is 'bimodal', being just a smoothed version of the inviscid one. (For definition of 'bimodal' and 'unimodal' see Makarov et al. 1990.)

Region II is the range $10^{-3}<d<2$. Viscous effects are important throughout the beam and the velocity profile changes as $d$ is increased, starting 'bimodal' and becoming 'unimodal', and becoming very close to the similarity profile at about $d=$ 2.

Region III is the range $d>2$ and the similarity solution applies everywhere there. The velocity profile is 'unimodal'.


Figure 6. Schematic diagram of regions I, II and III of the ( $\left.s_{+} / a, 1 / \lambda\right)$-plane.
In figure 6 we have sketched regions I, II and III.
A different split involves $s_{+}$.
In the region $\left|s_{+}\right| \leqslant a$ the $\psi_{+}$and $\psi_{-}$beams overlap.
In the region $\left|s_{+}\right|>3 a$, for all practical purposes when $\lambda$ is small, the $\psi_{-}$solution can be ignored within the region defined by the $\psi_{+}$beam.

### 4.4. Validity of our boundary-layer approximation

As we pointed out in $\S 3$ expressions (3.3) and (3.4) for $\psi_{+}$and $\psi_{-}$satisfy (2.9) and (2.10) respectively that were derived from the exact equations (2.6) and (2.8) by introducing the 'boundary-layer approximation'. For $\psi_{+}$this approximation assumes that its derivatives with respect to $\sigma_{+}$are much larger than its derivatives with respect to $s_{+}$. We now investigate the validity of this assumption.

We will assume that it is satisfied in regions where

$$
\begin{equation*}
\left|\frac{\partial \psi_{+}}{\partial s_{+}}\right| \ll\left|\frac{\partial \psi_{+}}{\partial \sigma_{+}}\right| . \tag{4.13}
\end{equation*}
$$

Now, integration of (2.9) with respect to $\sigma_{+}$gives

$$
\begin{equation*}
\frac{\partial \psi_{+}}{\partial s_{+}}+\frac{\mathrm{i} \nu}{2 \omega \eta}\left(\frac{\partial^{3} \psi_{+}}{\partial \sigma_{+}^{3}}\right)=f\left(s_{+}\right), \tag{4.14}
\end{equation*}
$$

and $f\left(s_{+}\right)$must vanish since both terms on the left-hand side of (4.14) tend to zero as $\sigma_{+}$tends to plus or minus infinity. Hence

$$
\begin{equation*}
\frac{\partial \psi_{+}}{\partial s_{+}}+\frac{\mathrm{i} \nu}{2 \omega \eta}\left(\frac{\partial^{3} \psi_{+}}{\partial \sigma_{+}^{3}}\right)=0 . \tag{4.15}
\end{equation*}
$$

Hence, in terms of $w$ defined in (4.3), the condition (4.13) can be written

$$
\begin{equation*}
\lambda\left|\frac{\partial^{3} \psi_{+}}{\partial w^{3}}\right| \ll\left|\frac{\partial \psi_{+}}{\partial w}\right| . \tag{4.16}
\end{equation*}
$$

In discussing this condition, we consider the regions I, II and III of the $\left(s_{+} / a, 1 / \lambda\right)$ plane that were defined before and are shown schematically in figure 6 .

In region III, the similarity solution holds, so that $\psi_{+}$is given by

$$
\begin{equation*}
\psi_{+}=-\mathrm{i} \frac{\alpha_{+} a}{2 d^{1 / 3}} \int_{0}^{\infty} \exp \left(-k^{3}+\mathrm{i} k \zeta\right) \mathrm{d} k=-\mathrm{i} \frac{\alpha_{+} a}{2 d^{1 / 3}} e_{0}(\zeta) \tag{4.17}
\end{equation*}
$$

where

$$
\begin{equation*}
\zeta=\frac{\sigma_{+} / a}{\left(\lambda s_{+} / a\right)^{1 / 3}}=\frac{w}{d^{1 / 3}} \tag{4.18}
\end{equation*}
$$

is the similarity parameter, and $e_{0}(\zeta)$ is a function of $\zeta$.
Equation (4.7) etc. then gives

$$
r=\frac{\left|\partial \psi_{+} / \partial s_{+}\right|}{\left|\partial \psi_{+} / \partial \sigma_{+}\right|}=\frac{\lambda}{d^{2 / 3}} e_{r}(\zeta)
$$

where $e_{r}(\zeta)$ is a function of $\zeta$. Hence, at fixed $\zeta, r$ is a monotonic decreasing function of $d$ in region III: its maximum is attained at the boundary and is $\lambda 2^{-2 / 3} e_{r}(\zeta)$. Hence, as $\lambda$ is small, the boundary-layer approximation is satisfied in region III.

We now consider regions I and II. In terms of $I_{e}(0 ; w, d)$ and $I_{o}(0 ; w, d)$, the inequality (4.13) is satisfied provided

$$
\begin{equation*}
\lambda\left|I_{2}\right|=\lambda\left|\frac{\partial^{2} I_{0}}{\partial w^{2}}\right| \ll\left|I_{0}\right| \quad \text { for } \quad I_{n}=I_{e}(n ; w, d)+\mathrm{i} I_{o}(n ; w, d) \tag{4.19}
\end{equation*}
$$

An extensive study of the ratio $R=\left|I_{2} / I_{0}\right|$ is given in Hurley \& Keady (1996). The numerical calculations indicate that $R(w, d)<200$ for $d>1 / 16$ and all $w ; R(w, d)<$ 200 for $|w-1|>1 / 16$ and all $d$. In the region away from $d$ small and $w$ near 1,200 is much higher than needed, numbers less than eight being more appropriate. For given $d, s_{+} / a=d / \lambda$ which in the $\left(s_{+} / a, 1 / \lambda\right)$-plane are straight lines through the origin. For all points on a particular line, the values of $I_{n}$ will be the same. Hence the inequality (4.16) will be satisfied for $\lambda$ sufficiently small. It is clear from the plots of the profiles of the inviscid solution that are given in Part 1 that the curvature of the profiles and hence $\left|I_{2}\right|$ increases as $d$ decreases, so that the required value of $\lambda$ for inequality (4.16) to be satisfied will decrease. However, it is also clear that, if we fix $s_{+} / a, 0<s_{+} / a<\infty$, for $\lambda$ sufficiently small (depending on $s_{+} / a$ ), inequality (4.16) will be satisfied.

However, the boundary-layer approximation is clearly not satisfied in the neighbourhoods of the points where the characteristics touch the cylinder. We now give some attention to this small region. Consider the point $\sigma_{+} / a=-1, s_{+} / a=0$. Put $\sigma_{+}^{\prime}=\sigma_{+} / a, s_{+}^{\prime}=s_{+} / a$. On the halfline $s_{+}^{\prime}=0, \sigma_{+}^{\prime}<-1, \psi_{+}$has the inviscid values given in Part 1 so that $\partial \psi_{+} / \partial \sigma_{+}$has an inverse square-root singularity at $s_{+}^{\prime}=0, \sigma_{+}^{\prime}=-1$. Hence, if the boundary-layer approximation were valid, (2.9) would hold and $\partial \psi_{+} / \partial s_{+}$ would be more singular and hence of greater magnitude near the singular point. It follows that the appropriate approximation to (2.6) is the one which retains the highest derivatives, namely

$$
\nabla^{4} \psi_{+}=0
$$

The solution of this equation which has the appropriate behaviour on $s_{+}^{\prime}=0, \sigma_{+}^{\prime}<-1$ is

$$
\psi_{+}=2^{1 / 2} \alpha_{+} a r^{1 / 2} \sin \left(\frac{1}{2} \theta\right)
$$

where the notation is $r=\left[\left(1+\sigma_{+}^{\prime}\right)^{2}+\left(s_{+}^{\prime}\right)^{2}\right]^{1 / 2}$ and $\theta$ is a polar angle. The preceding equation shows that $\psi_{+}$, and hence $\partial \psi_{+} / \partial \sigma_{+}^{\prime}$, is even about the line $\theta=\pi$ and that both
are continuous on it. Also $\partial \psi_{+} / \partial s_{+}^{\prime}$ is odd about the line $\theta=0$ and vanishes on it. It is also clear from (2.6) applied with $\psi$ replaced by $\psi_{+}$that the region in which it reduces to $\nabla^{4} \psi_{+}=0$ is of diameter order $\lambda^{1 / 2}$.

## 5. Comparison of results with those of other investigators

### 5.1. The force exerted by the cylinder on the fluid

Lighthill $(1978, \S 4.10)$ considers a cylindrical wire oscillating horizontally and shows that in our notation

$$
\begin{equation*}
q=\frac{G \sin (\mu)}{4 \pi N} \int_{0}^{\infty} k_{0} \exp \left(-k_{0}^{3} \lambda s_{+}+\mathrm{i} k_{0} \sigma_{+}\right) \mathrm{d} k_{0} \tag{5.1}
\end{equation*}
$$

where $G$ is the force per unit length which the cylinder exerts on the fluid and $q$ is the vertical component of the mass flux. Thus

$$
\begin{equation*}
q=\rho_{0} \frac{\partial \psi_{+}}{\partial \sigma_{+}} \sin (\mu) \tag{5.2}
\end{equation*}
$$

where $\rho_{0}$ is the density. Putting $K=k_{0} a$, equation (5.1) gives

$$
\begin{equation*}
\frac{\partial \psi_{+}}{\partial \sigma_{+}}=\frac{G}{4 \pi \rho_{0} a^{2} N} \int_{0}^{\infty} K \exp \left(-K^{3} \lambda \frac{s_{+}}{a}+\mathrm{i} K \frac{\sigma_{+}}{a}\right) \mathrm{d} K \tag{5.3}
\end{equation*}
$$

We recognize the integral in this equation as giving the similarity solution of Thomas \& Stevenson (1972).

We interpret Lighthill's wire as being a circular cylinder of very small radius so that we compare his result with our asymptotic one given in (4.7). Using (3.7) and (3.5) with $V=0$ gives

$$
\begin{equation*}
\frac{\partial \psi_{+}}{\partial \sigma_{+}}=\frac{U}{4}(\cos (\mu)-\mathrm{i} \sin (\mu)) \int_{0}^{\infty} K \exp \left(-K^{3} \lambda \frac{s_{+}}{a}+\mathrm{i} K \frac{\sigma_{+}}{a}\right) \mathrm{d} K, \quad \lambda \frac{s_{+}}{a} \gg 1 \tag{5.4}
\end{equation*}
$$

Comparison of (5.3) and (5.4) gives

$$
\begin{equation*}
G=\pi \rho_{0} a^{2} N U[\cos (\mu)-\mathrm{i} \sin (\mu)] \tag{5.5}
\end{equation*}
$$

It is interesting to compare this result with that given by the inviscid theory of Part 1. Equation (3.43) therein shows that the force per unit length that the cylinder exerts on the fluid is

$$
\begin{equation*}
-F_{x}=\pi \rho_{0} \omega a^{2} \eta U \tag{5.6}
\end{equation*}
$$

This result is expected to hold approximately for the viscous case when $\lambda \ll 1$, for then the discussion at the end of $\S 4.4$ suggests that the inviscid solution will be a good approximation everywhere on the surface of the cylinder except very near where the characteristics touch it. Equations (5.5) and (5.6) give

$$
\begin{equation*}
\frac{G}{-F_{x}}=[1-\mathrm{i} \tan (\mu)] \tag{5.7}
\end{equation*}
$$

5.2. The work of Makarov et al. (1990)

We focus on this reference because it includes a comprehensive review of the theoretical and experimental work in Russia on a variety of problems involving internal waves. In model 4 of their paper they calculate the internal waves produced by a vibrating
circular cylinder in a viscous fluid. Their equation (4) for the vertical desplacement $h$ of the fluid particles is, in our notation,

$$
\begin{equation*}
h=-\frac{1}{2} \exp (-\mathrm{i} \omega t) a_{0} \sin \mu \sin \left(\mu-\phi_{0}\right) \int_{0}^{\infty} J_{1}(K) \exp \left(\mathrm{i} K \frac{\sigma_{+}}{a}-K^{3} \lambda \frac{s_{+}}{a}\right) \mathrm{d} K \tag{5.8}
\end{equation*}
$$

where $a_{0}$ is the amplitude of the particle displacement and $\phi_{0}$ is its inclination to the horizontal. The particle displacement $h_{\sigma_{+}}$in the direction of $\hat{\boldsymbol{\sigma}}_{+}$(defined in figure 5 of Part 1) is $h / \sin \mu$ and differentiation with respect to $t$ gives that the particle velocity in the direction of $\hat{\boldsymbol{\sigma}}_{+}$is

$$
\begin{equation*}
\frac{\partial \psi_{+}^{M}}{\partial \sigma_{+}}=-\frac{\mathrm{i}}{2} \exp (-\mathrm{i} \omega t) a_{0} w \sin \left(\mu-\phi_{0}\right) \int_{0}^{\infty} J_{1}(K) \exp \left(\mathrm{i} K \frac{\sigma_{+}}{a}-K^{3} \lambda \frac{s_{+}}{a}\right) \mathrm{d} K \tag{5.9}
\end{equation*}
$$

where the superscript $M$ denotes Makarov et al. (1990). (Also, in (5.9), $t$ is measured from $t_{0}=-\pi / w$ to change the sign preceding its right-hand side.) Noting that

$$
\begin{equation*}
a_{0} w \sin \left(\mu-\phi_{0}\right)=U \sin \mu-V \cos \mu \tag{5.10}
\end{equation*}
$$

(5.9) can be written

$$
\begin{equation*}
\frac{\partial \psi_{+}^{M}}{\partial \sigma_{+}}=-\frac{\mathrm{i}}{2} \exp (-\mathrm{i} \omega t)(U \sin \mu-V \cos \mu) \int_{0}^{\infty} J_{1}(K) \exp \left(\mathrm{i} K \frac{\sigma_{+}}{a}-K^{3} \lambda \frac{s_{+}}{a}\right) \mathrm{d} K \tag{5.11}
\end{equation*}
$$

The corresponding result in our solution with the time factor $\exp (-\mathrm{i} \omega t)$ added is

$$
\begin{align*}
\frac{\partial \psi_{+}}{\partial \sigma_{+}}=-\frac{\mathrm{i}}{2} \exp (-\mathrm{i} \omega t)[U \sin \mu-V \cos \mu+\mathrm{i}( & U \cos \mu+V \sin \mu)] \\
& \times \int_{0}^{\infty} J_{1}(K) \exp \left(\mathrm{i} K \frac{\sigma_{+}}{a}-K^{3} \lambda \frac{s_{+}}{a}\right) \mathrm{d} K . \tag{5.12}
\end{align*}
$$

We now compare our results with the experimental ones shown in their figure $3(b)$. For their experiments we find $\lambda$ to be approximately 0.0019 . Hence, using our figure 5 , we find that the particle displacement on the centreline of the beam is approximately 0.61 mm which is in reasonable agreement with their experimental results. However, they state that their theoretical and experimental results differ by a factor of 6.5 .

Finally, we consider results for the phase difference between the left- and right-hand beams versus the angle of inclination, ${ }_{0}$, of the plane of oscillation to the horizontal. Their figure 2 shows excellent agreement between their theory and experiment. Our equations (3.3)-(3.6) give

$$
\begin{equation*}
\alpha_{-} / \alpha_{+}=\exp \left(\mathrm{i}\left(\pi-2_{0}\right)\right), \tag{5.13}
\end{equation*}
$$

so that our results also agree with their experimental ones.
We can summarize the comparison of our results with those of Makarov et al. as follows. It is clear from (5.11) and (5.12) that both $\psi_{+}^{M}$ and $\psi_{+}$satisfy the same partial differential equation, namely (2.9). Also, (4.1), (4.2) and (4.8) of Part 1 make it clear that both $\psi_{+}+\psi_{-}$and $\psi_{+}^{M}+\psi_{-}^{M}$ satisfy the same (inviscid) boundary condition, namely (2.16). However, when the viscosity is taken to be zero $\psi_{+}$reduces to the exact solution discussed in Part 1 but $\psi_{+}^{M}$ does not and is therefore unsatisfactory.

## 6. Application of results to a general elliptic cylinder

It is pointed out at the end of Appendix B that our approximate solution for general ellipses is given by

$$
\begin{array}{ll}
\psi_{+}=\mp \mathrm{i} \alpha_{+} c_{+} \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\mp K^{3} \lambda_{+} \frac{s_{+}}{c_{+}} \pm \mathrm{i} K \frac{\sigma_{+}}{c_{+}}\right) \mathrm{d} K, & \pm s_{+}>0, \\
\psi_{-}= \pm \mathrm{i} \alpha_{-} c_{-} \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\mp K^{3} \lambda_{-} \frac{s_{-}}{c_{-}} \mp \mathrm{i} K \frac{\sigma_{-}}{c_{-}}\right) \mathrm{d} K, & \pm s_{-}>0 \tag{6.2}
\end{array}
$$

on the understanding that the solution (6.1) for $s_{+}>0$ is continued up to the righthand boundary of the ellipse shown in figure 8(b) in Appendix B. Similarly the solution for $s_{+}<0$ is continued up to the left-hand boundary of the ellipse.

In (6.1) and (6.2) $c_{+}, c_{-}, \alpha_{+}$and $\alpha_{+}$are given by (3.14), (3.26) and (3.27) of Part 1. Also, $\lambda_{+}$and $\lambda_{-}$are defined by

$$
\begin{equation*}
\lambda_{+}=\frac{v}{2 c_{+}^{2} w \eta}, \quad \lambda_{-}=\frac{v}{2 c_{-}^{2} w \eta}, \tag{6.3}
\end{equation*}
$$

see (3.1) herein.
Acknowledgements are gratefully given to the referees for helpful and constructive comments and for drawing our attention to several important references.

## Appendix A. Derivation of equation (3.7)

A.1. Fourier transforms in $\sigma$

We focus on the beam of waves in the first quadrant.
Define

$$
\begin{gather*}
\sigma_{+}^{\prime}=\sigma_{+} / c_{+} \quad \text { and } s_{+}^{\prime}=s_{+} / c_{+},  \tag{A1}\\
\ell_{+}\left(\psi_{+}\right) \equiv \frac{\partial^{2} \psi_{+}}{\partial \sigma_{+}^{\prime} \partial s_{+}^{\prime}}+\cot (2 \mu) \frac{\partial^{2} \psi_{+}}{\partial s_{+}^{\prime 2}}+\mathrm{i} \lambda_{+}\left(\frac{\partial^{4} \psi_{+}}{\partial \sigma_{+}^{\prime 4}}+2 \frac{\partial^{4} \psi_{+}}{\partial \sigma_{+}^{\prime 2} \partial s_{+}^{\prime 2}}+\frac{\partial^{4} \psi_{+}}{\partial s_{+}^{\prime 4}}\right), \tag{A2}
\end{gather*}
$$

where $\lambda_{+}$is defined in (6.3), and

$$
\begin{equation*}
\ell_{+, 3}\left(\psi_{+}\right) \equiv \frac{\partial^{2} \psi_{+}}{\partial \sigma_{+} \partial s_{+}}+\mathrm{i} \lambda_{+}\left(\frac{\partial^{4} \psi_{+}}{\partial \sigma_{+}^{4}}\right) . \tag{A3}
\end{equation*}
$$

In terms of these, (2.6) and (2.9) become respectively

$$
\begin{array}{r}
\ell_{+}\left(\psi_{+}\right)=0, \\
\ell_{+, 3}\left(\psi_{+}\right)=0, \tag{A5}
\end{array}
$$

both to be satisfied in the flow region. We always solve $\ell_{+}(\psi)=0$ with boundary conditions that $\psi$ and $\nabla \psi$ tend to zero at infinity. To save unnecessary writing, henceforth in this Appendix we drop the superscript prime (or equivalently take $c_{+}=$ 1).

Assume that the singularities of $\psi$ are fairly mild so that we can define

$$
\begin{equation*}
\Psi_{+}(K)=\frac{1}{\sqrt{ } 2 \pi} \int_{-\infty}^{\infty} \psi_{+} \exp \left(-\mathrm{i} K \sigma_{+}\right) \mathrm{d} \sigma_{+} \tag{A6}
\end{equation*}
$$



Figure 7. Roots of the quartic for $\mu=\pi / 4$ (and $K>0$ ). The line shown is $f=-\xi K / \lambda_{+}$: the quartic is $f=\left(\xi^{2}-K^{2}\right)^{2}$. Their points of intersection, the real roots, are denoted $\xi_{j},-K<\xi_{2}<0, \xi_{3}<-K$.
as the Fourier transform of $\psi_{+}$, with inversion formula

$$
\begin{equation*}
\psi_{+}=\frac{1}{\sqrt{ } 2 \pi} \int_{-\infty}^{\infty} \Psi_{+} \exp \left(\mathrm{i} K \sigma_{+}\right) \mathrm{d} K . \tag{A7}
\end{equation*}
$$

Taking a Fourier transform of $\ell_{+}\left(\psi_{+}\right)=0$, see (A 2), gives

$$
\begin{equation*}
\frac{\mathrm{d}^{4} \Psi_{+}}{\mathrm{d} s_{+}^{4}}-\frac{\mathrm{d}^{2} \Psi_{+}}{\mathrm{d} s_{+}^{2}}\left(2 K^{2}+\frac{\mathrm{i} \cot (2 \mu)}{\lambda_{+}}\right)+\frac{K}{\lambda_{+}} \frac{\mathrm{d} \Psi_{+}}{\mathrm{d} s_{+}}+K^{4} \Psi_{+}=0 \tag{A8}
\end{equation*}
$$

The equation

$$
\begin{equation*}
\Psi_{+}=\Psi_{0,+}(K) \exp \left(\zeta s_{+}\right) \tag{A9}
\end{equation*}
$$

is a solution of (A 8) if

$$
\begin{equation*}
\zeta^{4}-\zeta^{2}\left(2 K^{2}+\mathrm{i} \frac{\cot (2 \mu)}{\lambda_{+}}\right)+\zeta \frac{K}{\lambda_{+}}+K^{4}=0 . \tag{A10}
\end{equation*}
$$

Employing the method of the Principle of the Argument we find that the quartic polynomial (A 10 ) has (for $\mu \neq \pi / 4$ ) one zero in each of the four quadrants of the ( $\zeta=\xi+\mathrm{i} \eta$ )-plane. We denote by $\zeta_{i}$ the zero in the $i$ th quadrant.

When $K>0$, the most general solution of (A 8) that decays for large positive $s_{+}$is

$$
\begin{equation*}
\Psi_{+}=c_{2}\left(K ; \lambda_{+}\right) \exp \left(\zeta_{2} s_{+}\right)+c_{3}\left(K ; \lambda_{+}\right) \exp \left(\zeta_{3} s_{+}\right) . \tag{A11}
\end{equation*}
$$

## A.2. Roots of the quartic, $\mu=\pi / 4$

We temporarily consider $\mu=\pi / 4$. Then (A 10 ) has one zero in each of the first and fourth quadrants and two on the negative $\xi$-axis and can be written

$$
\begin{equation*}
\left(\zeta^{2}-K^{2}\right)^{2}+\zeta K / \lambda_{+}=0, \tag{A12}
\end{equation*}
$$

so that the two zeros on the negative $\xi$-axis satisfy

$$
\begin{equation*}
\left(\xi^{2}-K^{2}\right)^{2}+\xi K / \lambda_{+}=0 . \tag{A13}
\end{equation*}
$$

The location of the two real roots of (A 13), denoted by $\xi_{2}$ and $\xi_{3}$, are illustrated in figure 7.

We now examine $\xi_{3}$. Refer again to figure 7 . We see that when $\left(K / \lambda_{+}\right) \geqslant 1$, $f=-K \xi / \lambda_{+}$is nearly vertical, so that one root $\xi_{3}$ is large and negative,

$$
\xi_{3} \sim-\left(K / \lambda_{+}\right)^{1 / 3}, \quad K / \lambda_{+} \rightarrow \infty,
$$

and the other real root $\xi_{2}$ is very nearly zero. This small root of (A 13 ) is approximated, at fixed $K>0$, by

$$
\begin{equation*}
\xi_{2}=-\lambda_{+} K^{3}\left(1-2\left(\lambda_{+} K^{2}\right)^{2}+9\left(\lambda_{+} K^{2}\right)^{4}+\ldots\right) \quad \text { for } \quad \lambda_{+} \rightarrow 0+. \tag{A14}
\end{equation*}
$$

Also, $\xi_{2}$ can be approximated, at fixed $\lambda_{+}>0$, by

$$
\xi_{2} \sim-K+\frac{1}{2 \lambda_{+}^{1 / 2}}-\frac{1}{64 K^{2} \lambda_{+}^{3 / 2}} \text { for } K \rightarrow+\infty
$$

On $s_{+}=0$, equation (A 11) gives $\Psi_{+}=c_{2}(K)+c_{3}(K)$ so that

$$
\begin{equation*}
\psi_{+}=\frac{1}{\sqrt{ } 2 \pi} \int_{-\infty}^{\infty}\left(c_{2}(K)+c_{3}(K)\right) \exp \left(\mathrm{i} K \sigma_{+}\right) \mathrm{d} K, \quad s_{+}=0 \tag{A15}
\end{equation*}
$$

On taking

$$
\begin{equation*}
\left(c_{2}(K)+c_{3}(K)\right)=-\mathrm{i} \sqrt{ } 2 \pi \alpha_{+} c_{+} \frac{J_{1}(K)}{K} H(K), \tag{A16}
\end{equation*}
$$

where $H(K)$ denotes the Heaviside step function, which is 1 for $K>0$ and 0 for $K<0$, equation (A 11) and the inversion formula give $\psi_{+}$that agree with the inviscid solution as $s_{+}$tends to zero from above.
Now when $\lambda_{+}$is small and $s_{+}>0$, the $c_{3}(K)$-term is negligible compared to the $c_{2}(K)$ term. This is established by the results of the preceding subsection concerning the roots of the quartic. From this, we obtain that, for $s_{+}>0$, we obtain correct asymptotics by replacing $c_{2}(K)$ by zero. Also, using the asymptotics of $\xi_{2}$ for $\lambda_{+}$small, we see that we obtain correct asymptotics by replacing $\xi_{2}$ by $-\lambda_{+} K^{3}$. This gives a derivation of (3.7).

## A.3. Return to the derivation of (3.7)

We now return to the general case when $\mu \neq \pi / 4$. Putting $\cot (2 \mu)=\epsilon$, we find that the root equation (A 10) that reduces to $-\lambda_{+} K^{3}$ as $\epsilon \rightarrow 0$ has a positive imaginary part and is in the second quadrant. Thus, again for $\lambda_{+}$small, our proposed solution is

$$
\begin{equation*}
\psi_{+}=-\mathrm{i} \alpha_{+} c_{+} \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\zeta_{2} s_{+}^{\prime}+\mathrm{i} K \sigma_{+}^{\prime}\right) \mathrm{d} K, \quad s_{+}^{\prime} \geqslant 0 \tag{A17}
\end{equation*}
$$

where $\zeta_{2}$ is the root of equation (A 10) that lies in the second quadrant of the complex $\zeta$-plane. When $\lambda_{+}$is small, the quartic (A 10 ) is now approximated by

$$
\begin{equation*}
K^{4}+\zeta K / \lambda_{+}=0, \tag{A18}
\end{equation*}
$$

so that

$$
\zeta=-\lambda_{+} K^{3}
$$

and (A 17) becomes (3.7).
However, (A 17) has one major defect, because it may readily be shown that it gives values of $\partial \psi_{+} / \partial s_{+}$which are not continuous on $s_{+}=0,\left|\sigma_{+}\right|>1$. However, (3.7) does not have this defect, as was shown in $\S 3.1$ of the main text.

We note that $\psi_{+}$given by (3.7) satisfies (A 5) exactly but (A 4) only approximately.

## Appendix B. Representation of the solution by distributions of semivortices

We are concerned with developing a representation of our solution by a distribution of singular solutions in the case $\lambda \ll 1$ when the viscous solution tends to the inviscid one close to the cylinder. The first step is to find such a representation for the inviscid solution given by (3.35)-(3.37) of Part 1.

## B.1. The inviscid case

Makarov et al. (1990) expressed their solution in terms of a distribution of dipoles. We prefer to use vortices.

The solution for a point vortex in a stratified fluid was given by Robinson (1969) for the case when the fluid was confined above and below by two horizontal plane walls. The solution was adapted by Hurley (1969) to the case of an unbounded fluid. Thus in accordance with his equation (3.18) we take as the singular solution

$$
\begin{align*}
\psi_{V} & =(1 / \pi) \log \left(\sigma_{+} \sigma_{-}\right) \\
& =\mathrm{i}\left[2-H\left(\sigma_{+}\right)-H\left(\sigma_{-}\right)\right]+(1 / \pi) \log \left|\sigma_{+} \sigma_{-}\right|, \quad x>0 \tag{B1}
\end{align*}
$$

and $\psi_{V}$ is defined to be an even function of $x$.
We express
where

$$
\left.\begin{array}{rl}
\psi_{V} & =\psi_{V+}+\psi_{V-}, \\
\psi_{V+}\left(\sigma_{+}\right) & =(1 / \pi) \log \sigma_{+}  \tag{B2}\\
\psi_{V-}\left(\sigma_{-}\right) & =(1 / \pi) \log \sigma_{-} ;
\end{array}\right\}
$$

nd
$\psi_{V+}$ and $\psi_{V-}$ will be referred to as 'semi-vortices' because their sum is a vortex. The Green's function for the antisymmetric motion of a flat plate was shown in Hurley (1969) to be, in our notation, proportional to

$$
\begin{equation*}
g\left(s^{\prime}\right)=\frac{s^{\prime}}{\left(1-s^{\prime 2}\right)^{1 / 2}} \tag{B3}
\end{equation*}
$$

where $s^{\prime}=s / a$ and $s$ is the distance of a point on the plate from its centre, the length of the plate being $2 a$. Define $\sigma_{+}^{\prime}=\sigma_{+} / a, \sigma_{-}^{\prime}=\sigma_{-} / a, \tau_{+}^{\prime}=\tau_{+} / a, \tau_{-}^{\prime}=\tau_{-} / a$. We now show that the solutions for a circular cylinder can be expressed as

$$
\left.\begin{array}{l}
\psi_{+}=\frac{\alpha_{+} a}{\pi} \int_{\Gamma_{+}} \frac{\tau_{+}^{\prime} \log \left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right)}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}} \mathrm{~d} \tau_{+}^{\prime} \\
\psi_{-}=\frac{\alpha_{-} a}{\pi} \int_{\Gamma_{-}} \frac{\tau_{-}^{\prime} \log \left(\tau_{-}^{\prime}-\sigma_{-}^{\prime}\right)}{\left(1-\tau_{-}^{\prime 2}\right)^{1 / 2}} \mathrm{~d} \tau_{-}^{\prime} \tag{B4}
\end{array}\right\}
$$

where $\Gamma_{+}$and $\Gamma_{-}$are the interval $(-1,1)$ of the $O \tau_{+}^{\prime}$ and $O \tau_{-}^{\prime}$ axes shown in figure $8(a)$. $\Gamma_{+}$is indented below $\tau_{+}=\sigma_{+}$for $s_{+}>0$ and above it for $s_{+}<0$.

Differentiation of the first of (B4) gives

$$
\begin{aligned}
\frac{\partial \psi_{+}}{\partial \sigma_{+}} & = \pm \frac{\mathrm{i} \alpha_{+} \sigma_{+}^{\prime}}{\left(1-\sigma_{+}^{\prime 2}\right)^{1 / 2}}+\frac{\alpha_{+}}{\pi} \mathscr{P} \int_{-1}^{1} \frac{\tau_{+}^{\prime} \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}\left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right)}, \quad\left|\sigma_{+}^{\prime}\right|<1 \\
& =\frac{\alpha_{+}}{\pi} \int_{-1}^{1} \frac{\tau_{+}^{\prime} \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}\left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right)}, \quad\left|\sigma_{+}\right|>1
\end{aligned}
$$

where $\mathscr{P}$ denotes the Cauchy principal value, and where in the first equation the upper sign is for $s_{+}>0$ and the lower sign for $s_{+}<0$.

Using the results

$$
\mathscr{P} \int_{-1}^{1} \frac{\tau_{+}^{\prime} \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{2}\right)^{1 / 2}\left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right)}=\pi
$$



Figure 8. Location of semi-vortices for (a) circular cylinders, (b) elliptic cylinders.
and

$$
\int_{-1}^{1} \frac{\tau_{+}^{\prime} \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}\left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right)}=1+\left\{\begin{array}{clc}
\frac{-\sigma_{+}^{\prime}}{\left(\sigma_{+}^{\prime 2}-1\right)^{1 / 2}} & \text { for } & \sigma_{+}^{\prime}>1 \\
\frac{+\sigma_{+}^{\prime}}{\left(\sigma_{+}^{\prime 2}-1\right)^{1 / 2}} & \text { for } & \sigma_{+}^{\prime}<-1
\end{array}\right.
$$

we find that $\partial \psi_{+} / \partial \sigma_{+}$takes the values given by (3.30) of Part 1 as desired.

## B.2. The viscous case

Equations (B 2) and (B 4) show that the inviscid solution for $\psi_{+}$can be expressed as

$$
\begin{equation*}
\psi_{+}=\alpha_{+} a \int_{\Gamma_{+}} \frac{\tau_{+}^{\prime} \psi_{V+}\left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right) \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}}, \tag{B5}
\end{equation*}
$$

where $\psi_{V+}\left(\sigma_{+}\right)$is given by (B 2 ).

Now it can be shown that $\psi_{V+}$ is the solution, having appropriate behaviour at large distances, of the equation

$$
\begin{equation*}
\eta^{2} \frac{\partial^{2} \psi_{V+}}{\partial x^{\prime 2}}-\frac{\partial^{2} \psi_{V+}}{\partial y^{\prime 2}}=-2 \mathrm{i} \delta\left(x^{\prime}\right) \delta\left(y^{\prime}\right) \tag{B6}
\end{equation*}
$$

Thus referring to equation (2.2) of the main text and (B5) and (B6) above we take as the viscous solution

$$
\begin{equation*}
\psi_{+}^{v}=\alpha_{+} a \int_{\Gamma_{+}} \frac{\tau_{+}^{\prime} \psi_{V+}^{v}\left(\tau_{+}^{\prime}-\sigma_{+}^{\prime}\right) \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}} \tag{B7}
\end{equation*}
$$

where $\psi_{V+}^{v}$ satisfies

$$
\begin{equation*}
\eta^{2} \frac{\partial^{2} \psi_{V+}^{v}}{\partial x^{\prime 2}}-\frac{\partial^{2} \psi_{V+}^{v}}{\partial y^{\prime 2}}+\mathrm{i} \lambda \nabla^{4} \psi_{V+}^{v}=-2 \mathrm{i} \delta\left(x^{\prime}\right) \delta\left(y^{\prime}\right) \tag{B8}
\end{equation*}
$$

The solution of (B8) clearly tends to that of (B6) as $\lambda$ tends to zero. Using (2.6) we see that referred to the $\left(\sigma_{+}^{\prime}, s_{+}^{\prime}\right)$ axes (B 8$)$ is

$$
\begin{equation*}
\frac{\partial^{2} \psi_{V+}^{v}}{\partial \sigma_{+}^{\prime} \partial s_{+}^{\prime}}+\cot (2 \mu) \frac{\partial^{2} \psi_{V+}^{v}}{\partial s_{+}^{\prime 2}}+\mathrm{i} \lambda \nabla^{4} \psi_{V+}^{v}=-2 \mathrm{i} \delta\left(\sigma_{+}^{\prime}\right) \delta\left(s_{+}^{\prime}\right) \tag{B9}
\end{equation*}
$$

Let

$$
\bar{\psi}_{V+}^{v}=\frac{1}{2 \pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \psi_{V+}^{v} \exp \left(-\mathrm{i} K \sigma_{+}^{\prime}-\mathrm{i} k s_{+}^{\prime}\right) \mathrm{d} \sigma_{+}^{\prime} \mathrm{d} s_{+}^{\prime},
$$

so that by (B 9)

$$
\bar{\psi}_{V+}^{v}=\frac{-\mathrm{i}}{\pi\left(-k K-k^{2} \cot (2 \mu)+\mathrm{i} \lambda\left(K^{4}+2 K^{2} k^{2}+k^{4}\right)\right.}
$$

This gives

$$
\begin{equation*}
\psi_{V+}^{v}=\frac{-\mathrm{i}}{2 \pi^{2}} \int_{-\infty}^{\infty} \int_{0}^{\infty} \frac{\exp \left(+\mathrm{i} K \sigma_{+}^{\prime}+\mathrm{i} k s_{+}^{\prime}\right) \mathrm{d} K \mathrm{~d} k}{-k K-k^{2} \cot (2 \mu)+\mathrm{i} \lambda\left(K^{2}+k^{2}\right)^{2}} \tag{B10}
\end{equation*}
$$

where only those waves having positive values of $K$ are included so that the radiation condition is satisfied.

We carry out the integration with respect to $k$ first. Let $D(k)=-k K-k^{2}$ $\cot (2 \mu)+\mathrm{i} \lambda\left(K^{2}+k^{2}\right)^{2}$, so that

$$
\begin{equation*}
D(-\mathrm{i} \zeta)=\mathrm{i} \lambda\left[\zeta^{4}+\zeta^{2}\left(2 K^{2}+\mathrm{i} \cot (2 \mu) / \lambda\right)+K \zeta / \lambda+K^{4}\right] \tag{B11}
\end{equation*}
$$

We note that the above polynomial in $\zeta$ is the same as the left-hand side of (A 10). This polynomial has roots at $\zeta_{i}, i=1,2,3,4$. The corresponding zeros of $D(k)$ are $k_{i}=-\mathrm{i} \zeta_{i}$. We find that $k_{2}$ and $k_{3}$ are in the upper half-plane and $k_{1}$ and $k_{4}$ are in the lower halfplane. It was shown in Appendix A that in the limit $\lambda \rightarrow 0$ the contribution from $\zeta_{2}$ was dominant. Hence

$$
\begin{align*}
\psi_{V+}^{v} & \sim \frac{-1}{\pi} \int_{0}^{\infty} \frac{\exp \left(+\mathrm{i} K \sigma_{+}^{\prime}+\zeta_{2} s_{+}^{\prime}\right)}{K} \mathrm{~d} K, \quad s_{+}>0, \lambda \rightarrow 0 \\
& \sim \frac{-1}{\pi} \int_{0}^{\infty} \frac{\exp \left(+\mathrm{i} K \sigma_{+}^{\prime}-\lambda K^{3} s_{+}^{\prime}\right)}{K} \mathrm{~d} K \tag{B12}
\end{align*}
$$

using (A 14). Substitution into (B7) gives

$$
\begin{equation*}
\psi_{+}^{v}=\frac{-\alpha_{+} a}{\pi} \int_{0}^{\infty} \frac{\exp \left(-\mathrm{i} K \sigma_{+}^{\prime}-\lambda K^{3} s_{+}^{\prime}\right)}{K} I(K) \mathrm{d} K, \quad s_{+}>0 \tag{B13}
\end{equation*}
$$

where

Noting that

$$
I(K)=\int_{-1}^{1} \frac{\tau_{+}^{\prime}}{\left(1-\tau_{+}^{\prime 2}\right)^{1 / 2}} \exp \left(\mathrm{i} K \tau_{+}^{\prime}\right) \mathrm{d} \tau_{+}^{\prime}
$$

equation (B 13) gives

$$
\int_{-1}^{1} \frac{\tau_{+}^{\prime} \exp \left(\mathrm{i} K \sigma_{+}^{\prime}\right) \mathrm{d} \tau_{+}^{\prime}}{\left(1-\tau_{+}^{2}\right)^{1 / 2}}=\mathrm{i} \pi J_{1}(K),
$$

$$
\psi_{+}^{v}=-\mathrm{i} \alpha_{+} a \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\mathrm{i} K \sigma_{+}^{\prime}-\lambda K^{3} s_{+}^{\prime}\right) \mathrm{d} K,
$$

in agreement with (3.3) of the main text.
We now consider the problem for the general ellipse shown in figure $8(b)$, where $A B$ is the straight line joining the points where the ellipse touches the characteristics $\sigma_{+}= \pm c_{+}$.

It is clear from the discussion in $\S 3.2$ that the viscous solution given by (B 7) (with $\alpha_{+}$having the appropriate value given by (3.26) of Part 1) will approximate the inviscid solution on the portion of the ellipse to the right of the line $A B$ with arbitrarily small relative error with $\lambda$ sufficiently small provided that the $O \tau_{+}$-axis is taken to be to the left of $A B$. The solution to the left of $A B$ may similarly be constructed if the $O \tau_{+}$-axis is taken to be to the right of $A B$. Hence we can replace (3.3) by

$$
\begin{equation*}
\psi_{+}=\mp \mathrm{i} \alpha_{+} c_{+} \int_{0}^{\infty} \frac{J_{1}(K)}{K} \exp \left(\mp K^{3} \lambda_{+} s_{+} / c_{+} \pm \mathrm{i} K \sigma_{+}^{\prime} / c_{+}\right) \mathrm{d} K, \quad \pm s_{+}>0 \tag{B13}
\end{equation*}
$$

on the understanding that the solution for $s_{+}>0$ is continued up to the right-hand boundary of the ellipse shown in figure 8(b). Similarly for $+s_{+}<0$.

In (B13) $c_{+}$and $\alpha_{+}$are given by (3.14) and (3.26) of Part 1 and

$$
\begin{equation*}
\lambda_{+}=\frac{\nu}{2 \chi_{+}^{2} \omega \eta}, \tag{B14}
\end{equation*}
$$

see (3.1) herein.

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